

Contents

1	Introduction	1
2	Continuum mechanics and theory of inelastic material behaviour	5
2.1	Continuum mechanical preparations	5
2.1.1	Balance equations	6
2.1.2	Thermodynamics with internal variables	6
2.1.3	Phase transformations	8
2.1.4	Heat equation	10
2.1.5	Mechanics	13
2.2	Specific cases of inelastic material behaviour	15
2.2.1	Classical plasticity	15
2.2.2	Modelling of creep	18
2.2.3	Material laws for TRIP	19
2.2.4	Modelling using multi-mechanism models	21
2.3	Modelling of phase transformations during heating and austenitisation	21
2.4	Problem setting	24
3	Multi-mechanism models	27
3.1	General introduction	27
3.1.1	General multi-mechanism models (in series)	28
3.2	Two-mechanism models	30
3.2.1	Two-mechanism models with one criterion (2M1C) for plasticity	31
3.2.2	Two-mechanism models with two criteria (2M2C) for plasticity	36
3.3	Modelling of creep by means of two-mechanism models	40
3.3.1	Modelling of creep using a 2M1C model	40
3.3.2	Modelling of creep using a 2M2C model	43
3.3.3	Thermodynamic consistency	45
3.4	A two-mechanism model for the modelling of creep and TRIP . . .	47
3.4.1	Evolution equations	48
3.4.2	Thermodynamic consistency	50
4	Model verification and parameter identification	51
4.1	Preliminaries	51
4.1.1	Three-dimensional setting for a one-dimensional stress state	51
4.1.2	One-dimensional version of material laws	53
4.2	Deriving further data from uniaxial experiments	54

4.3	Verification of material laws using uniaxial experimental data	56
4.3.1	Direct problem: General strain-driven approach	57
4.3.2	Direct problem: General stress-driven approach	59
4.4	Verification of material laws for creep	60
4.4.1	Discretised version of the model equations (1D)	60
4.4.2	Direct problem: Strain-driven approach for creep	60
4.4.3	Direct problem: Stress-driven approach for creep	62
4.5	Verification of material laws for TRIP	63
4.5.1	Discretised version of the model equations (1D)	63
4.5.2	Strain-driven approach for TRIP	63
4.5.3	Stress-driven approach for TRIP	64
4.6	Parameter identification	65
4.6.1	Experimental data	65
4.6.2	General strategy	66
4.6.3	Parameter identification in the case of creep	67
4.6.4	Parameter identification for TRIP	70
5	Discretisation of the 3D model	71
5.1	Weak formulation	71
5.1.1	Weak form of heat equation	72
5.1.2	Weak form of deformation equation	73
5.2	Numerical solution scheme	74
5.2.1	Time discretisation	74
5.2.2	Spatial discretisation	75
5.2.3	Overall solution scheme	75
5.3	Application of the Finite Element Method	76
5.3.1	Discretised heat equation	76
5.3.2	Phase transitions	77
5.3.3	Discretised deformation equation	78
5.3.4	Strain and stress tensor	78
5.4	Numerical algorithm for the calculation of inelastic quantities	79
5.4.1	Algorithm for creep	80
5.4.2	Algorithm for creep with a back stress	81
5.4.3	Algorithm in the case of creep without back stress	85
6	Simulation results, validation with experimental data	89
6.1	Creep of the bearing steel SAE 52100 (100Cr6) (1D case)	90
6.1.1	Results from uniaxial experiments	90
6.1.2	Results from parameter identifications	94
6.2	Creep and TRIP of the bearing steel SAE 52100 (100Cr6) (1D case)	100
6.2.1	Experimental results	101
6.2.2	Simulation results	101
6.3	3D Simulation and validation with workpiece experiments	106
6.4	Creep during heating and austenitisation (3D case)	108
6.4.1	3D Simulation of a beam	108

6.4.2	Evolution in single nodes of geometry	118
6.4.3	Validation by experimental data	125
6.4.4	3D Simulation of a steel ring	129
7	Outlook	133
A	Semi-implicit version of numerical algorithm	135
	Bibliography	139