

Table of Contents

Notation	ix
Abstract	xi
Deutsche Kurzfassung	xiii
1 Introduction	1
1.1 Motivation	1
1.2 Research topic overview	2
1.2.1 Distributed MPC	3
1.2.2 Economic MPC	5
1.3 Contributions and outline of this thesis	6
2 Background	9
2.1 Stabilizing MPC	9
2.2 Economic MPC	11
2.2.1 Average performance, optimal steady-state operation and stability .	12
2.2.2 Average constraints	15
2.3 Summary	16
3 Distributed MPC for cooperative control	19
3.1 Problem setup	19
3.2 Distributed MPC schemes for general cooperative control problems	23
3.2.1 Distributed MPC with general cost functions	23
3.2.2 Distributed MPC with separable cost functions	29
3.2.3 Discussion	32
3.3 Application to consensus and synchronization	34
3.3.1 Example - synchronization of linear oscillators	38
3.4 Summary	39
4 Economic MPC: Dissipativity, average constraints, and self-tuning terminal cost	41
4.1 Dissipativity in economic MPC	41
4.1.1 Necessity of dissipativity for optimal steady-state operation	41
4.1.2 Robustness of dissipativity under changing constraint sets	50
4.2 Average constraints	60
4.2.1 Economic MPC with average constraints and terminal region	61
4.2.2 Convergence in economic MPC with average constraints	69
4.2.3 Economic MPC with transient average constraints	74
4.2.4 Numerical Examples	81

4.3	Economic MPC with self-tuning terminal cost	85
4.3.1	Problem setup	85
4.3.2	Average performance with time-varying terminal weight	88
4.3.3	Self-tuning terminal weights	90
4.3.4	Discussion	96
4.3.5	Numerical examples	98
4.4	Summary	100
5	Distributed economic MPC	103
5.1	Problem setup and distributed economic MPC scheme	104
5.2	Convergence analysis of distributed economic MPC	109
5.3	Application: Consensus under conflicting objective	114
5.4	Summary and discussion	115
6	Conclusions	117
6.1	Summary and discussion	117
6.2	Outlook	118
A	Stability of discrete-time systems	123
A.1	Stability and asymptotic stability	123
A.2	Asymptotic and essential convergence	124
B	Nonlinear programming	125
	Bibliography	127